Generative models

Outline

1. Preview: Auto-Encoders, VAE
2. Generative models with GAN
3. GAN architectures

Drawing? => learning from examples
Recall Algo GAN

for number of training iterations do
    for \( k \) steps do
        ● Sample minibatch of \( m \) noise samples \( \{\tilde{z}^{(1)}, \ldots, \tilde{z}^{(m)}\} \) from noise prior \( p_{\tilde{z}}(\tilde{z}) \).
        ● Sample minibatch of \( m \) examples \( \{x^{(1)}, \ldots, x^{(m)}\} \) from data generating distribution \( p_{\text{data}}(x) \).
        ● Update the discriminator by ascending its stochastic gradient:
          \[
          \nabla_{\theta_d} \frac{1}{m} \sum_{i=1}^{m} \left[ \log D(x^{(i)}) + \log \left( 1 - D\left(G\left(z^{(i)}\right)\right) \right) \right].
          \n          \]
    end for
    ● Sample minibatch of \( m \) noise samples \( \{z^{(1)}, \ldots, z^{(m)}\} \) from noise prior \( p_{\tilde{z}}(\tilde{z}) \).
    ● Update the generator by descending its stochastic gradient:
      \[
      \nabla_{\theta_g} \frac{1}{m} \sum_{i=1}^{m} \log \left( 1 - D\left(G\left(z^{(i)}\right)\right) \right).
      \]
end for

Functions \( G \) and \( D \) are NN.

Question:
Which architectures for \( G \) and \( D \)?
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   1. Basics
Basic Archi for G and D and expe

Models
G and D fully connected nets
or convolutional for D, (de)convolutional for G (as seen for segmentation nets)
ReLU and/or sigmoids, dropout

Datasets
MNIST, Toronto Face Database, CIFAR-10

GAN - Evaluation

- Approximate $p_g$ by fitting a Gaussian Parzen window on the generated images.
- Cross-validate $\sigma$ to maximize likelihood of validation set
- Compute the likelihood of the test set

Evaluation not trivial, can be done using generated images as inputs for deep nets $\Rightarrow$ inception scores
Figure: Right col nearest from dataset. a) MNIST, b) TFD, c) CIFAR-10 (fully connected), d) CIFAR-10 (convolutional $D$, deconvolutional $G$)
GAN - Qualitative results 2/2

Figure: Linear interpolation between 2 points in z space

- **Advantages:**
  - Computational advantages (no complex likelihood inference)
  - Can represent sharper distributions

- **Disadvantages:**
  - $G$ and $D$ must be well synchronized for the algorithm to converge correctly
GAN architectures

• How to improve result quality?
  • Spatial resolution
    ⇒ Cascade of GAN
  • Object quality
    => Progressive growing of spatial resolution in G
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   2. LaPGAN
Laplacian Pyramid GANs (LAPGANs)

- GANs do not work well for complex / high level / natural images.
- Idea: decompose the generation in successive tasks using Laplacian Pyramid (of GANs)

Let \( d(I) \) and \( u(I) \) be down-sampling and up-sampling operations. Gaussian pyramid:

\[
G(I) = [l_0, l_1, \ldots, l_K], \quad l_k = d^{(k)}(l)
\]

Laplacian pyramid:

\[
h_k = L_k(l) = l_k - u(l_{k+1})
\]

Reconstruction:

\[
l_k = u(l_{k+1}) + h_k
\]
LAPGAN model - sampling

- Set of generative convnets: $G_0, \ldots, G_K$
- Generated details: $\tilde{h}_k = G_k(z_k, u(\tilde{l}_{k+1}))$
- Reconstructed image: $\tilde{l}_k = u(\tilde{l}_{k+1}) + \tilde{h}_k$ ($\tilde{l}_{K+1} = 0$)
LAPGAN model - training

- Low-pass version of $l_0$: $l_0 = u(d(l_0)$
- Either:
  - High-pass version of $l_0$: $h_0 = l_0 - l_0$
  - Generate $\tilde{h}_0 = G_0(z_0, l_0)$
- Forward $D_0(l_0 + h_0$ or $\tilde{h}_0$)
- Backward $D_0$ and $G_0$
- $G_K$ and $D_K$ are trained as a simple GAN
LAPGAN model - Experiments

- **Datasets**: CIFAR-10, STL

- **Initial scale**:
  - $G_K$ and $D_K$ have 2 hidden layers and ReLU
  - $z_K \sim U_{[-1,1]}^{100}$
  - Trained as GAN

- **Subsequent scales**:
  - $G_k$ and $D_k$ convnets with 3 and 2 layers
  - $z_k \sim U_{[-1,1]}^{\|k\|}$ (“color” layer)
  - Trained as CGAN
LAPGAN model - Results - CIFAR
LAPGAN model - Results - STL

Figure 4: STL samples: (a) Random 96x96 samples from our LAPGAN model. (b) Coarse-to-fine generation chain.
LAPGAN model - Results - LSUN
LAPGAN

• Good idea (cascade) but Generator structure too weak

=> Other approach: progressive growing of spatial resolution
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Progressive growing of spatial resolution in G

Deep Convolutional GANs (DCGANs)

GANs are hard to scale => Identify a family of architectures that gives stable training

- Replace any pooling layers with strided convolutions (discriminator) and fractional-strided convolutions (generator)
- Use batchnorm in both the generator and the discriminator
- Remove fully connected hidden layers for deeper architectures
- Use ReLU activation in generator for all layers except for the output, which uses Tanh
- Use LeakyReLU activation in the discriminator for all layers
Progressive growing of spatial resolution in G: DCGAN

Upsampling step by step

Combine with convolutional layers
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   4. ProGAN
Progressive growing of GANs

[Progressive Growing of GANs for Improved Quality, Stability and Variation, Tero Karras et al. (NVIDIA); ICLR 2018]

1. First, start with training 4x4 output images.
2. When this training has converged, add a new block to generate 8x8 output images.
3. Etc.

The transition to adding a new block is gradual, we first start with more weight on the (upsampled) output of the previous block, and then add more and more weight to the output of the current block.

All weights remain trainable during the whole process.

Discriminator = mirror image of generator
Figure 1: Our training starts with both the generator (G) and discriminator (D) having a low spatial resolution of $4 \times 4$ pixels. As the training advances, we incrementally add layers to G and D, thus increasing the spatial resolution of the generated images. **All existing layers remain trainable throughout the process.** Here $N \times N$ refers to convolutional layers operating on $N \times N$ spatial resolution. This allows stable synthesis in high resolutions and also speeds up training considerably. One the right we show six example images generated using progressive growing at $1024 \times 1024$. 
Progressive growing of GANs

[Progressive Growing of GANs for Improved Quality, Stability and Variation, Tero Karras et al. (NVIDIA); ICLR 2018]

Figure 2: When doubling the resolution of the generator (G) and discriminator (D) we fade in the new layers smoothly. This example illustrates the transition from $16 \times 16$ images (a) to $32 \times 32$ images (c). During the transition (b) we treat the layers that operate on the higher resolution like a residual block, whose weight $\alpha$ increases linearly from 0 to 1. Here $2 \times$ and $0.5 \times$ refer to doubling and halving the image resolution using nearest neighbor filtering and average pooling, respectively. The $\text{toRGB}$ represents a layer that projects feature vectors to RGB colors and $\text{fromRGB}$ does the reverse; both use $1 \times 1$ convolutions. When training the discriminator, we feed in real images that are downsampled to match the current resolution of the network. During a resolution transition, we interpolate between two resolutions of the real images, similarly to how the generator output combines two resolutions.
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   5. MSG-GAN
MSG-GAN: Multi-Scale Gradients for Generative Adversarial Networks [CVPR 2020]

Main Idea:
• ProGAN both use progressive growing, but although this gives stability, it introduces many complicated training parameters associated with each new network.
• Training cannot be done “out of the box”, have to adjust parameters for each new dataset.

→ Train all at once without complicated adding on layers
Figure 2: Architecture of MSG-GAN, shown here on the base model proposed in ProGANs [13]. Our architecture includes connections from the intermediate layers of the generator to the intermediate layers of the discriminator. Multi-scale images sent to the discriminator are concatenated with the corresponding activation volumes obtained from the main path of convolutional layers followed by a combine function (shown in yellow).
MSG-GAN: results – Random generated CelebA-HQ Faces at resolution 1024x1024
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   6. StyleGAN
StyleGAN: A Style-Based Generator Architecture for Generative Adversarial Networks [Karras CVPR 2019]

Still progressive growing architecture but with new refinement block based on: Arbitrary Style Transfer in Real-time with Adaptive Instance Normalization (AdaIN)

$$\text{AdaIN}(x, y) = \sigma(y) \left( \frac{x - \mu(x)}{\sigma(x)} \right) + \mu(y)$$
StyleGAN Network Architecture

(a) Traditional

Latent $z \in \mathcal{Z}$

- Normalize
- Fully-connected
- PixelNorm
- Conv 3x3
- PixelNorm
- Upsample
- Conv 3x3
- PixelNorm
- Conv 3x3
- PixelNorm
- Conv 3x3
- PixelNorm

... $\rightarrow 8 \times 8$

(b) Style-based generator

Latent $z \in \mathcal{Z}$

- Normalize
- Mapping network $f$
- AdaIN
- Conv 3x3
- AdaIN
- Conv 3x3
- AdaIN
- Conv 3x3
- AdaIN
- Conv 3x3
- AdaIN
- Conv 3x3
- AdaIN
- Conv 3x3
- AdaIN

Synthesis network $g$

- Const 4x4x512
- AdaIN
- 4x4
- Upsample
- Conv 3x3
- AdaIN
- 8x8

Noise

$\rightarrow B$

$\rightarrow A$
# Building up the Model

<table>
<thead>
<tr>
<th>Method</th>
<th>CelebA-HQ</th>
<th>FFHQ</th>
</tr>
</thead>
<tbody>
<tr>
<td>A Baseline Progressive GAN [29]</td>
<td>7.79</td>
<td>8.04</td>
</tr>
<tr>
<td>B + Tuning (incl. bilinear up/down)</td>
<td>6.11</td>
<td>5.25</td>
</tr>
<tr>
<td>C + Add mapping and styles</td>
<td>5.34</td>
<td>4.85</td>
</tr>
<tr>
<td>D + Remove traditional input</td>
<td>5.07</td>
<td>4.88</td>
</tr>
<tr>
<td>E + Add noise inputs</td>
<td><strong>5.06</strong></td>
<td>4.42</td>
</tr>
<tr>
<td>F + Mixing regularization</td>
<td>5.17</td>
<td><strong>4.40</strong></td>
</tr>
</tbody>
</table>
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4. Editing
DCGAN: Arithmetics in z space

Latent space analysis for GAN editing

Arithmetics in latent space
DCGAN
Walking in latent
Gan Editing
Latent space analysis for GAN editing